**Length: Maximum of 2 pages, including references.**

**TITLE (TIMES NEW ROMAN, UPPERCASE, font size 11)**

Author(s) Full name in Times New Roman Bold 11

Institution, country, and email in Times New Roman 11  
*(Include this information for each author)*

***Abstract:****100 words. Times New Roman 11. Line spacing 1.5*

***Keywords****: Maximum of four.*

**1. Introduction**

Times New Roman 11. *Line spacing 1.5*

**2. Methods**

Times New Roman 11. *Line spacing 1.5*

**3. Results**

Times New Roman 11. *Line spacing 1.5*. Tables and figures must follow APA format

**4. Discussion**

Times New Roman 11. *Line spacing 1.5*

**5. Conclusions**

Times New Roman 11. *Line spacing 1.5*

**6. References**

[APA](https://normas-apa.org/referencias/) Format. List only those cited in alphabetical order. Examples: [1] and [2].

[1] M. A. Gomes, G. L. M. Silveira, and A. A. G. Siqueira. Gait pattern adaptation for an active lower-limb orthosis based on neural networks. Advanced Robotics, 25(1):1903–1925, 2011.

[2] J C Perez Ibarra, W M Santos, H I Krebs, and A A G Siqueira. Adaptive impedance control for robot-aided rehabilitation of ankle movements. In 5th IEEE RAS & EMBS International Conference on Biomedical Robotics and Biomechatronics, pages 664–669, São Paulo, Brazil, 2014.